# **IR Optimization**

Ronghui Gu Spring 2024

Columbia University

\* Course website: https://verigu.github.io/4115Spring2024/



## Goal

- Runtime
- Memory usage
- Power Consumption

## Sources?

int	)	<;				
int y;						
bo	ol	b	1;			
bo	ol	b	2;			
bo	ol	b	3;			
b1	=	Х	+	х	<	у
b2	=	х	+	х	= :	= y
b3	=	х	+	х	>	у

int	)	<b>;</b>				
101	. )	/;				
bo	ol	p.	1;			
bo	ol	b:	2;			
bo	ol	b	3;			
b1	=	Х	+	Х	<	у
b2	=	х	+	х	= :	= у
b3	=	х	+	х	>	у

int	t)	<;				
int	ij	/;				
bo	ol	b	1;			
bo	ol	b	2;			
bo	ol	b	3;			
b1	=	х	+	х	<	у
b2	=	х	+	х	= :	= y
b3	=	х	+	х	>	у

# C code: while (x < y + z) {

x = x - y; }

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#### **Three-Address:**

\_Lo: \_to = y + z; \_t1 = x < \_to; bz \_L1 \_t1; x = x - y; jmp \_Lo; \_L1:

# 

**Optimal?** Undecidable!

Soundness: semantics-preserving

IR optimization v.s. code optimization:

 $x \ * \ 0.5 \Rightarrow x \ * \ 1$ 

Local optimization v.s. global optimization









# **Global Optimization**



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**Purpose:** remove the duplicate computation of "a op b" in Three-Address code.

vl = a op b

v2 = a op b

. . .

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v1 = a op b

. . .

v2 = a op b

If values of v1, a, and b have not changed, rewrite the code:

v1 = a op b

. . .

v2 = v1





#### C code: int a; int b; int c; a = 4; c = a + b; f(a + b);

#### Three-address code:

Do we need to replace \_t1 with c?

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c = a + b;<br/>f(a + b);

#### Three-address code:

Do we need to replace \_t1 with c? NO!

#### If we have

v1 = v2

then as long as v1 and v2 have not changed, we can rewrite

```
a = ... v1 ...
as
a = ... v2 ...
```



\_to = 4; a = \_to; \_t1 = a + b; c = \_t1; \_t2 = \_t1; param \_t2; call f;



\_to = 4; a = 4; \_t1 = a + b; c = \_t1; \_t2 = \_t1; param \_t2; call f;



\_to = 4; a = 4; \_t1 = a + b; c = \_t1; \_t2 = \_t1; param \_t2; call f;







# An assignment to a variable **v** is called dead if its value is never read anywhere.



\_to = 4; a = 4; \_t1 = 4 + b; c = \_t1; \_t2 = \_t1; param \_t1; call f;



\_to = 4; a = 4; \_t1 = 4 + b; c = \_t1; \_t2 = \_t1; param \_t1; call f;



#### C code: int a; int b; int c; a = 4; c = a + b; f(a + b);
#### C code:

#### Three-address code:



#### Arithmetic simplication:

• e.g., rewrite x = 4 \* a as x = a « 2

#### Constant folding:

• e.g., rewrite x = 4 \* 5 as x = 20

# **Implementing Local Optimization**

- Most optimizations are only possible given some analysis of the program's behavior.
- In order to implement an optimization, we will talk about the corresponding program analyses.

• Both common subexpression elimination and copy propagation depend on an analysis of the available expressions in a program.

## **Available Expressions**

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## **Available Expressions**

- Both common subexpression elimination and copy propagation depend on an analysis of the available expressions in a program.
- An expression is called available if some variable in the program holds the value of that expression.
- In common subexpression elimination, we replace an available expression requiring computation by the variable holding its value.
- In copy propagation, we replace the use of a variable by the available expression it holds that does not require computation.

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## Finding Available Expressions

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- · Whenever we execute a statement
  - a = expr
    - Any expression holding **a** is invalidated.
    - The expression **a** = **expr** becomes **available**.

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- Initially, no expressions are available
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- The expression **a** = **expr** becomes **available**.
- Algorithm: Iterate across the basic block, beginning with the empty set of expressions and updating available expressions at each variable.

{ }				
	a	=	b	;
	С	=	b	;
d	=	a	+	b;
e	=	a	+	b;
	d	=	b	;
f	=	a	+	b;

{} a = b;  $\{a = b\}$ c = b; d = a + b; e = a + b; d = b; f = a + b;

{ } a = b;  $\{a = b\}$ c = b;  $\{a = b, c = b\}$ d = a + b; e = a + b; d = b; f = a + b;

```
{ }
          a = b;
         \{a = b\}
          c = b;
     \{a = b, c = b\}
        d = a + b;
\{a = b, c = b, d = a + b\}
        e = a + b;
          d = b:
        f = a + b;
```

a = b; c = b; d = a + b; e = **d**; d = b; f = e;

```
{ }
          a = b;
         \{a = b\}
          c = b;
     \{a = b, c = b\}
       d = a + b;
\{a = b, c = b, d = a + b\}
         e = d;
          d = b:
          f = e;
```

f = e;

```
{ }
             a = b;
            \{a = b\}
              c = b;
         \{a = b, c = b\}
           d = a + b:
   \{a = b, c = b, d = a + b\}
             e = d:
\{a = b, c = b, d = a + b, e = d\}
             d = b:
     \{a = b, c = b, d = b\}
              f = e:
  \{a = b, c = b, d = b, f = e\}
```

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- A variable is live at a point in a program if later in the program its value will be read before it is written to again.
- Dead code elimination works by computing liveness for each variable, then eliminating assignments to dead variables.

## **Computing Live Variables**

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- To know if a variable will be used at some point, we iterate across the statements in a block in reverse order.
- Initially, some small set of values are known to be live (which ones depends on the particular program).
- When we see the statement: **a** = **b** op c
  - If **a** is not alive after the statement, skip it.
  - Otherwise, If **a** is alive after the statement
    - Just before the statement, **a** is not alive, since its value is about to be overwritten.
    - Just before the statement, both **b** and **c** are alive, since we're about to read their values.
  - (what if we have a = a op b?)

#### **Example: Liveness Analysis**

a = b; c = a; d = b + d;e = d; d = b; f = e + c; { d, e }
a = b; c = a; d = b + d;e = d; d = b; { d, e } f = e + c; { d, e }

a = b; c = a; d = b + d;e = d; { b, e } d = b; { d, e } f = e + c; { d, e }

a = b; c = a; { b, d } d = b + d: { b, d } e = d; { b, e } d = b; { d, e } f = e + c; { d, e }

{ b, d } a = b; { b, d } c = a; { b, d } d = b + d: { b, d } e = d; { b, e } d = b; { d, e } f = e + c; { d, e }

#### **Example: Dead Code Elimination**

{ b, d } a = b; { b, d } c = a; { b, d } d = b + d: { b, d } e = d; { b, e } d = b: { d, e } f = e + c; { d, e }

{ b, d } d = b + d; e = d;

> d = b; { d, e }

# **Global Optimization**

# Replace each variable that is known to be a constant value with the constant.

## **Global Constant Propagation**



## **Global Constant Propagation**



- Local dead code elimination needed to know what variables were live on exit from a basic block.
- This information can only be computed as part of a global analysis.
- How do we modify our liveness analysis to handle a CFG?

- In a local analysis, each statement has exactly one predecessor.
- In a global analysis, each statement may have multiple predecessors.
- A global analysis must combine information from all predecessors of a basic block.











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- Up to this point, we've considered loop-free CFGs, which have only finitely many possible paths.
- Not all possible loops in a CFG can be realized in the actual program.
- Sound approximation: Assume that every possible path through the CFG corresponds to a valid execution.
  - Includes all realizable paths, but some additional paths as well.
  - May make our analysis less precise (but still sound).
  - Makes the analysis feasible; we'll see how later.

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- In a global analysis with loops, every basic block might depend on every other basic block.

- In a local analysis, there is always a well-defined first statement to begin processing.
- In a global analysis with loops, every basic block might depend on every other basic block.
- To fix this, we need to assign initial values to all of the blocks in the CFG







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